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(54) **Cooperative positioning**

(57) A method to determine an own position comprises the steps of receiving position information of at least one object which transmits its own position information as reference position information, and deriving the own position on basis of a relative positioning calculation with the at least one received reference position information as reference. Therefore, a system enabling such a cooperative positioning comprises reference position sources (1), reference position sinks (2), reference position repeaters (4), and reference position refiners (3), wherein the latter comprise a reception means to receive position information, a position calculation means to derive an own position on basis of at least one received position information as reference position information, and a transmission means to transmit the received and/or calculated position information as reference position information upon request and/or within given time intervals, and the former three comprise respectively fewer functionality.

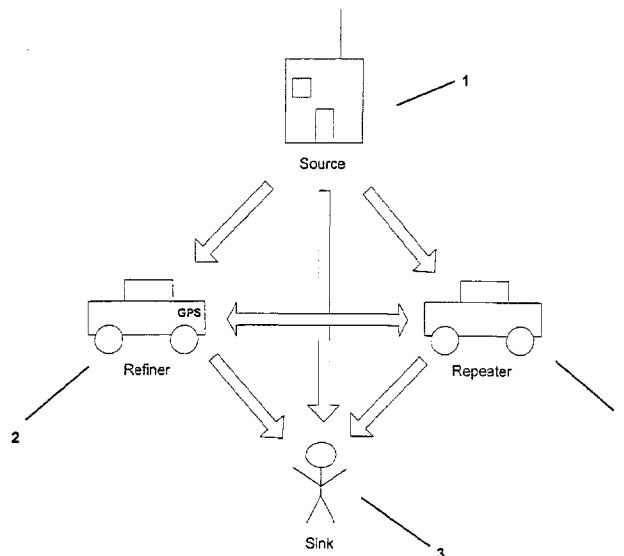


Fig. 1